

#### **Preliminary Data sheet**

NOVOHALL Rotary Sensor Touchless

RFE-3200 Voltage Mobile Applications











#### **Special Features**

- Touchless hall technology
- Electrical range up to 360°
- 2-part, mechanically decoupled
- High protection class IP67, IP68, IP69K
- Resolution up to 12 bit
- Wear-free
- Temperature range -40 °C to +125 °C
- Single and dual-channel versions
- Optimized for use in mobile applications with highest EMC requirements such as ISO pulses and high interferences to ISO 11452 and ECE-Standard
- Suitable for safety-related applications according to DIN EN ISO 13849
- Other configurations see separate data sheets

#### **Applications**

- Mobile working machines (industrial trucks, construction machinery, agricultural and forestry machinery)
- Marine applications

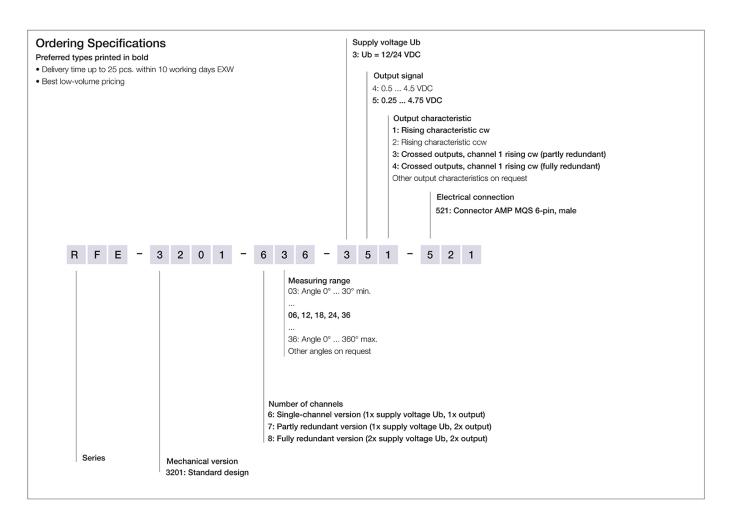
The two-part design consisting of sensor and magnetic position marker offers great flexibility when mounting. The absence of shaft and bearing makes the assembly much less sensitive to axial and radial application tolerances - separate couplings are obsolete. Measurements can be made transmissively through any non-ferromagnetic material.

The sensor is perfectly suitable for use in harsh environmental conditions through the completely encapsulated electronics. Single and dual-channel versions are available and suitable for use in safety-related applications.

Description	
Material	Housing: high grade, temperature resistant plastic PBT GF30 with SS inserts
Mounting	With 2 lens head screws M4x18 (included in delivery)
Fastening torque of mounting	max. 200 Ncm
Electrical connection	6-pin MQS-connector, code A, tinned contact according to drawing AMP-114-18063-126, Index A1 (Connector: AMP P/N 1-967616-1)
Mechanical Data	
Dimensions	See dimension drawing
Mechanical travel	360° continuous
Weight	approx. 50 g



# Ordering Specifications

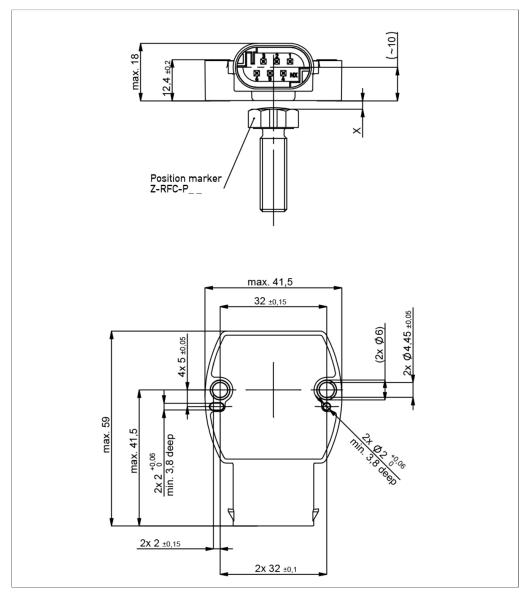


#### Accessories included in delivery

• 2x Lens head screws M4x18



## Drawing



CAD data see www.novotechnik.de/en/download/caddata/



When the marking of the position marker points towards the connector, the sensor is near the electrical center position.



## **Technical Data**

Туре	RFE-323521
Output signal	<b>Voltage</b> 0.25 4.75 V
Output signal	0.5 4.75 V
Load	∪.5 4.5 V ≥ 10 kΩ
Number of channels	1/2
Diagnosis	activated (in case of error, output signal is outside of the plausible signal range)
Update rate	typ. 3.4 kHz
Measuring range	0 30° up to 0 360° in 10°-steps
Independent linearity	≤ ±0.5 %FS
Resolution	12 bits
Repeatability	typ. ≤ ±0.1°
Hysteresis	typ. < ±0.1°
	Only easuring range 360°: typ. < 0.25° (lower hysteresis on request)
Temperature error	Measuring range 30 170°: typ. ±1.0 %FS, Measuring range ≥ 180°: typ. ±0.5 %FS
Supply voltage Ub	12/24 VDC (8 34 VDC)
Current consumption w/o load	typ. 12 mA per channel
Overvoltage protection	60 VDC (10 min.)
Polarity protection	yes (supply lines and outputs)
Short circuit protection	yes (vs. GND and supply voltage)
Insulation resistance (500 VDC)	≥ 10 MΩ
Environmental Data	
Max. operational speed	Mechanically unlimited
Vibration IEC 60068-2-6	20 g, 5 2000 Hz, Amax = 0.75 mm
Shock IEC 60068-2-27	50 g, 6 ms
Protection class ISO 20653	IP67 / IP68 / IP69K
Operating temperature	-40 +125°C*
	* The max. operating temperature depends on supply voltage Ub (see temp.diagram)
Life	Mechanically unlimited
Functional safety	Suitable for safety-related applications according to ISO 13849 after customer validation.
	Further safety data ( DCavg) and support for functional safety are available on request.
MTTF (IEC 60050)	447 years (per channel)
MTTFd (EN ISO 13849-1 parts count	894 years (per channel)
method, w/o load)	
MTTFd-certificate	https://www.novotechnik.de/en/downloads/certificates/mttfd-certificates/
Traceability	Serial number on type labeling: production batch of the sensor assembly and relevant sensor components
EMC Compatibility	
ISO 10605 ESD (Handling/Component)	8 kV / 15 kV
ISO 11452-2 Radiated HF-fields	100 V/m
ISO 11452-5 Radiated HF-Fields, stripline	200 V/m
CISPR 25 Radiated emission	Level 5
ISO 7637-2 Transient Emissions	Level 3
ISO 7637-2 Pulses on supply lines	(1, 2a, 2b, 3a, 3b, 4, 5) Level 4
ISO 7637-3 Pulses on output lines	Level 4
EN 13309 Construction machinery	
Emission/Immunity E1	acc. to ECE-R10
ISO 13766-1/-2 Construction machinery	On request



Connection Assignment

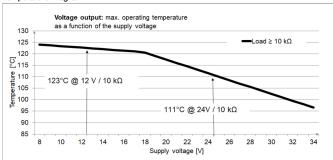
o o i i i o o i o i i i i o o i g i i i i				
Signal	Connector	Connector	Connector	
	code 5	code 5	code 5	
	Single-channel	Partly redundant	Fully redundant	
Supply voltage Ub 1	Pin 1	Pin 1	Pin 1	
GND 1	Pin 2	Pin 2	Pin 2	
Signal output 1	Pin 4	Pin 4	Pin 4	
Signal output 2	-	Pin 3	Pin 3	
Supply voltage Ub 2	-	-	Pin 6	
GND 2	-	-	Pin 5	
Not assigned	Pin 3, Pin 5, Pin 6	Pin 5, Pin 6	-	



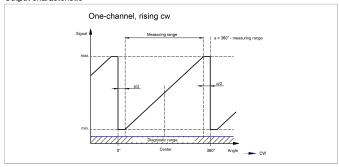


### **Technical Data** Output Characteristics

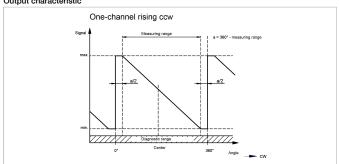
#### Temperature Diagram



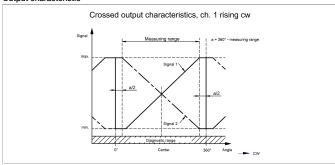
#### Output characteristic



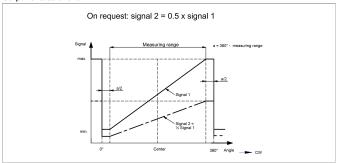
#### Output characteristic



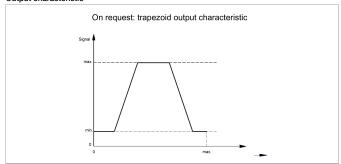
#### Output characteristic



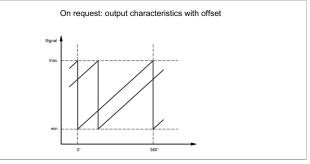
#### Output characteristic



#### Output characteristic

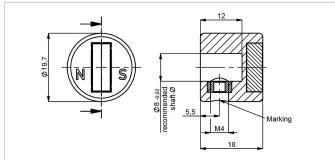


#### Output characteristic









#### Z-RFC-P23

Position marker for fixation with threaded pin M4 (included in delivery)

Caution: For orientation of the output

characteristic please follow the user manual of the position marker!

Material PA6-GF

Max. permitted ± 3 mm

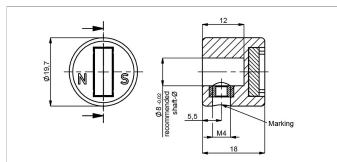
radial offset

 P/N
 Pack. unit [pcs]

 400056074
 1

 400056085
 25





#### Z-RFC-P43

Position marker for fixation with threaded pin M4 (included in delivery)

Caution: For orientation of the output characteristic please follow the user manual of

the position marker! Material PA6-GF

Max. permitted ± 3 mm

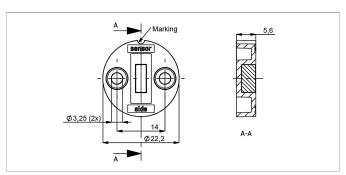
radial offset

 P/N
 Pack. unit [pcs]

 400105041
 1

 400105042
 25





#### Z-RFC-P30

Position marker for frontal fixation with 2 cylinder screws M3x8 (included in delivery)

Material PBT-GF

Max. permitted ± 1.5 mm

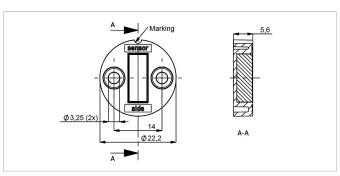
radial offset

 P/N
 Pack. unit [pcs]

 400056086
 1

 400056087
 25





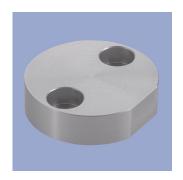
#### Z-RFC-P31

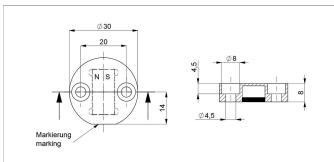
Position marker for frontal fixation with 2 cylinder

Max. permitted radial offset

P/N Pack. unit [pcs]
400056088 1
400056089 25







Position marker for frontal fixation with 2 cylinder head screws M4x20 (with microencapsulation, included in delivery).

Attention: Closed side of position marker faces the active side of sensor.

Material Aluminium, anodized

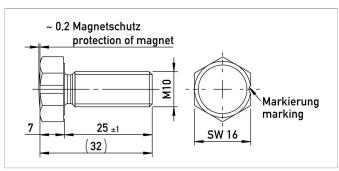
Max. permitted ± 4 mm

radial offset

Operating temp. -40 ... +125°C

P/N Pack. unit [pcs] 400106735 400106736 25





#### Z-RFC-P18

Screw position marker M10 x 25 mm, similar

DIN 933, magnet potted

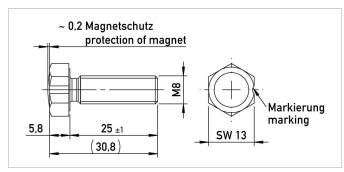
Material Aluminium, anodized

Max. permitted ± 3 mm

radial offset

P/N Pack. unit [pcs] 400104756 400104757 25





#### Z-RFC-P19

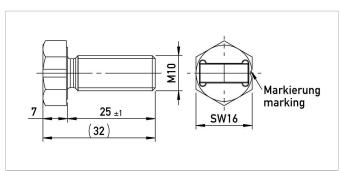
Screw position marker M8 x 25 mm, similar DIN 933/ISO 4017, magnet potted

Material Aluminium, anodized Max. permitted ± 1.5 mm

radial offset

P/N Pack. unit [pcs] 400104754 400104755 25





Screw position marker M10 x 25 mm, similar

DIN 933

Material Aluminium, anodized ± 3 mm

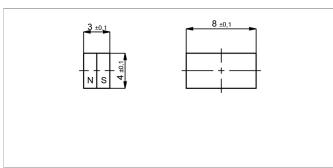
Max. permitted

radial offset

P/N	Pack. unit [pcs]
400104758	1
400104759	25







#### Z-RFC-P03

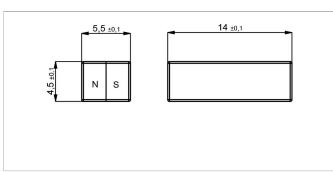
Magnet for direct application onto customer's shaft (see user manual).

We recommend mounting on non-magnetizable materials, otherwise the specified working distances will vary (e.g. reduction of approx. 20% with axial mounting on a magnetizable shaft).

Max. permitted ± 1.5 mm radial offset

P/N	Pack. unit [pcs]	_
400005658	1	_
400056081	50	





#### Z-RFC-P04

Magnet for direct application onto customer's shaft (see user manual).

We recommend mounting on non-magnetizable materials, otherwise the specified working distances will vary (e.g. reduction of approx. 20% with axial mounting on a magnetizable shaft). Max. permitted  $\pm 3$  mm

radial offset

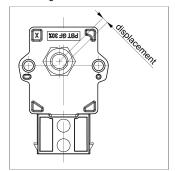
P/N	Pack. unit [pcs]
400005659	1
400056082	50



#### Working Distances Position Markers [mm] - Single-channel Versions

Z-RFC-P03 Z-RFC-P04 Z-RFC-P18 Z-RFC-P19 Z-RFC-P20 Z-RFC-P22 Z-RFC-P23 Z-RFC-P30 Z-RFC-P31	Z-RFC-P03	Z-RFC-P04	Z-RFC-P18	Z-RFC-P19	Z-RFC-P20	Z-RFC-P22	Z-RFC-P23	Z-RFC-P30	Z-RFC-P31	Z-RFC-P4
Z-RFC-P03 Z-RFC-P04 Z-RFC-P18 Z-RFC-P19 Z-RFC-P20 Z-RFC-P22 Z-RFC-P23 Z-RFC-P30 Z-RFC-P31	0.4 1.9	2 4.7	0 4	0 1.8	2 4.7	4.1 8.9	2 4.7	0.4 1.9	2 4.7	0 2.4
Z-RFC-P03 Z-RFC-P04 Z-RFC-P18 Z-RFC-P19 Z-RFC-P20 Z-RFC-P22 Z-RFC-P23 Z-RFC-P30 Z-RFC-P31										
	Working Distar	ces Position Mark	ers [mm] - Redund	lant Versions						
0 1.5					Z-RFC-P20	Z-RFC-P22	Z-RFC-P23	Z-RFC-P30	Z-RFC-P31	Z-RFC-P

#### Lateral Magnet Offset



Lateral magnet offset will cause additional linearity error. The angle error, which is caused by radial displacement of sensor and position marker depends on the used position marker or magnet.

#### Additional Linearity Error at Radial Displacement - Single-channel Versions

Z-RFC-P02 / P04 / P08	Z-RFC-P41 / P43 / P47	Z-RFC-P03 / P30	Z-RFC-P18	Z-RFC-P19	Z-RFC-P22
Z-RFC-P20 / P23 / P31					
0.5 mm: ±0.4°	0.5 mm: ±0.4°	0.5 mm: ±1.4°	0.5 mm: ±0.7°	0.5 mm: ±1.3°	1.0 mm: ±0.8°
1.0 mm: ±1.1°	1.0 mm: ±1.1°	1.0 mm: ±3.7°	1.0 mm: ±1.3°	1.0 mm: ±2.6°	2.0 mm: ±1.8°
2.0 mm: ±3.5°	2.0 mm: ±3.5°	2.0 mm: -	2.0 mm: ±3.3°	2.0 mm: -	4.0 mm: ±5.4°
Additional Linearity Error a	at Radial Displacement - Redun	dant Versions			
/	- D-0 D44 (D40 (D47	7 DEG DOG / DOG	7 050 040	7 050 040	- DF0 D00
Z-RFC-P02 / P04 / P08	Z-RFC-P41 / P43 / P47	Z-RFC-P03 / P30	Z-RFC-P18	Z-RFC-P19	Z-RFC-P22
Z-RFC-P20 / P23 / P31					
Z-RFC-P20 / P23 / P31	Z-RFC-P41 / P43 / P47 0.5 mm: ±0.7°	<b>Z-RFC-P03 / P30</b> 0.5 mm: ±2.5°	<b>Z-RFC-P18</b> 0.5 mm: ±1.1°	<b>Z-RFC-P19</b> 0.5 mm: ±2.3°	<b>Z-RFC-P22</b> 1.0 mm: ±1.1°
Z-RFC-P02 / P04 / P08 Z-RFC-P20 / P23 / P31 0.5 mm: ±0.7° 1.0 mm: ±1.8°					



# Connector System MQS



#### MQS Micro Quadlok System

Connector kit including

- 1 plug socket (female), AMP P/N 1-967616-1 6 tinned contacts for cable cross-section area 0.3 ... 0.5 mm<sup>2</sup> (AWG 22), AMP-P/N 963727-1
- 6 single conductor sealings AMP P/N 967067-2

P/N	Туре	
400005666	EEM-33-34	



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